

# DiffDock

## **Equivariant Diffusion Models** for Molecular Docking

#### **Gabriele Corso\***



#### Hannes Stärk\*







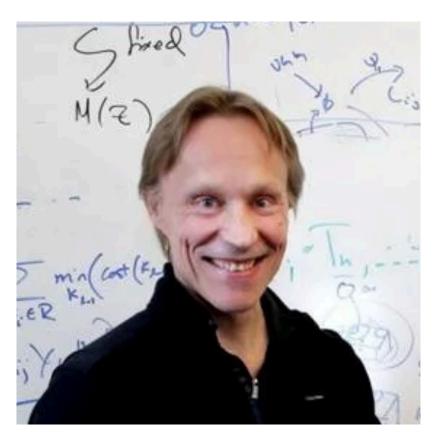
#### **Bowen Jing\***



#### **Regina Barzilay**

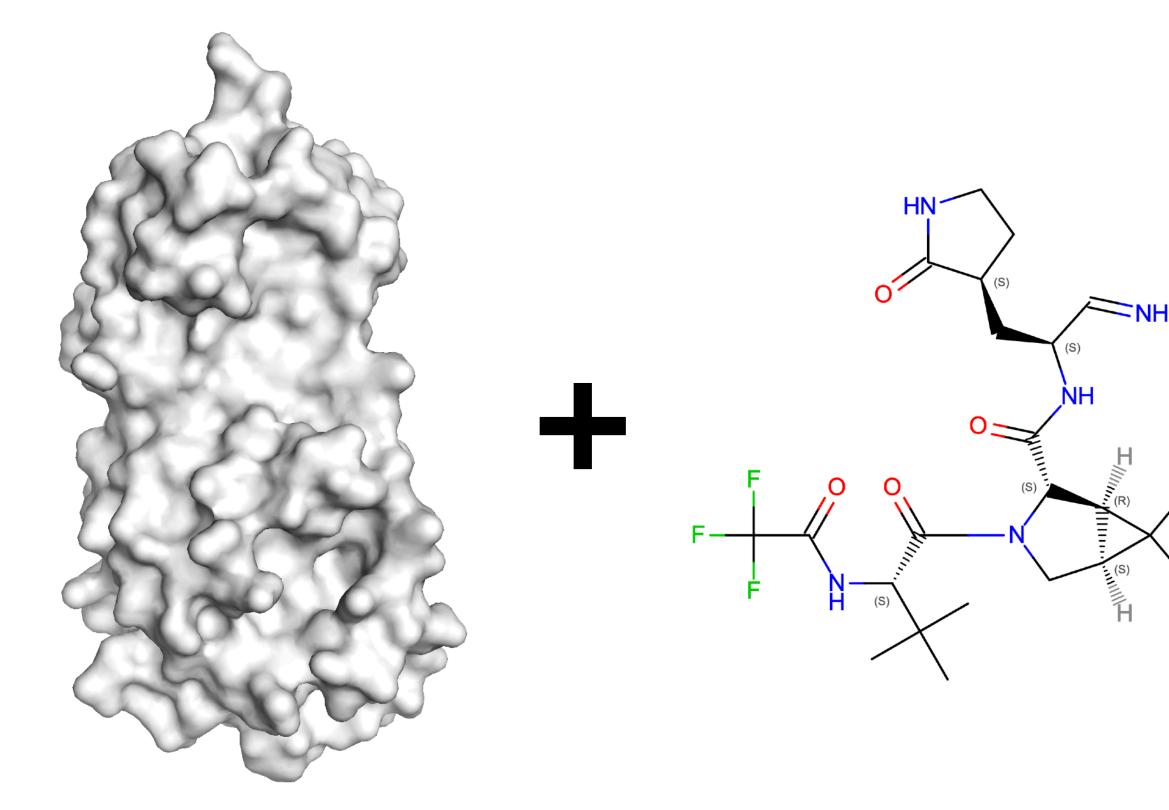


#### Tommi Jaakkola



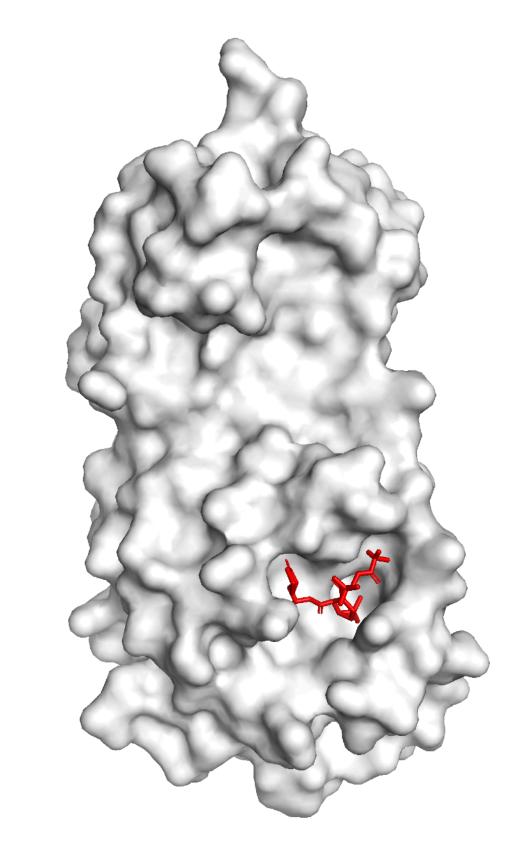


# **Blind Protein-Ligand Docking**



Input: protein structure + molecule



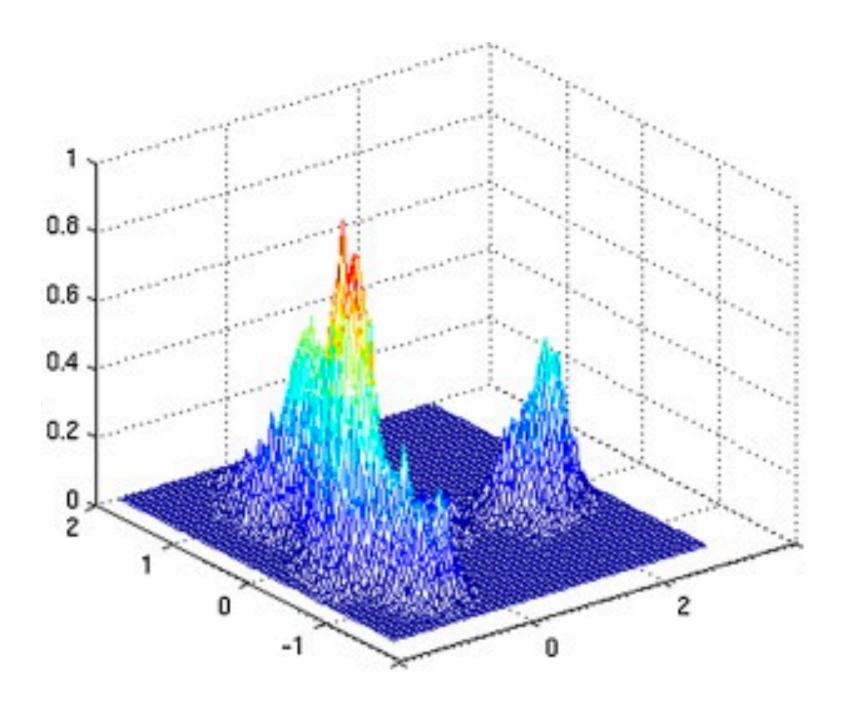


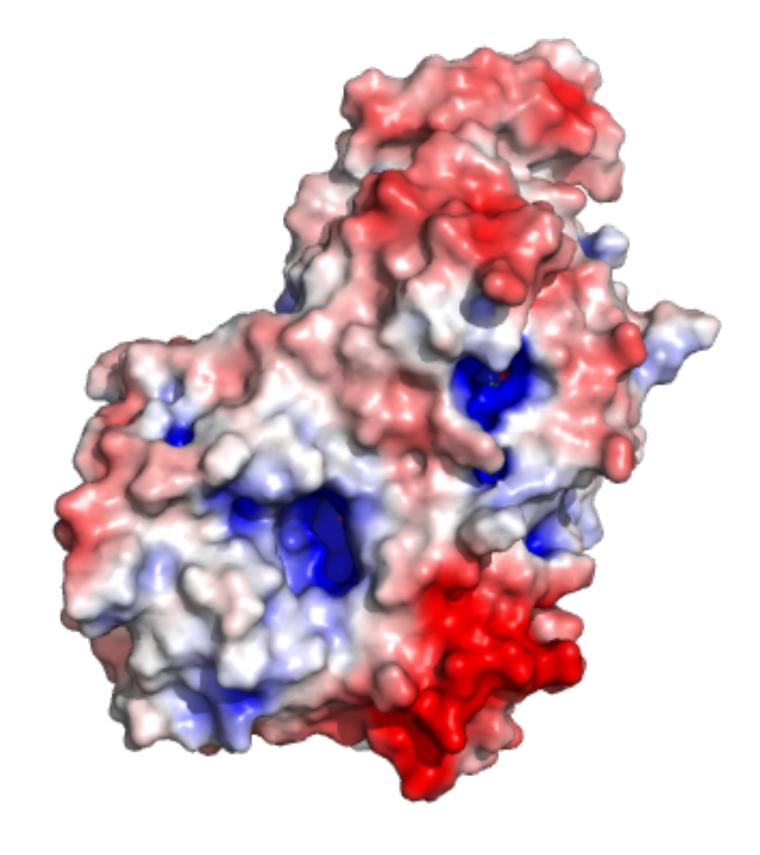
### **Output: bound structure**





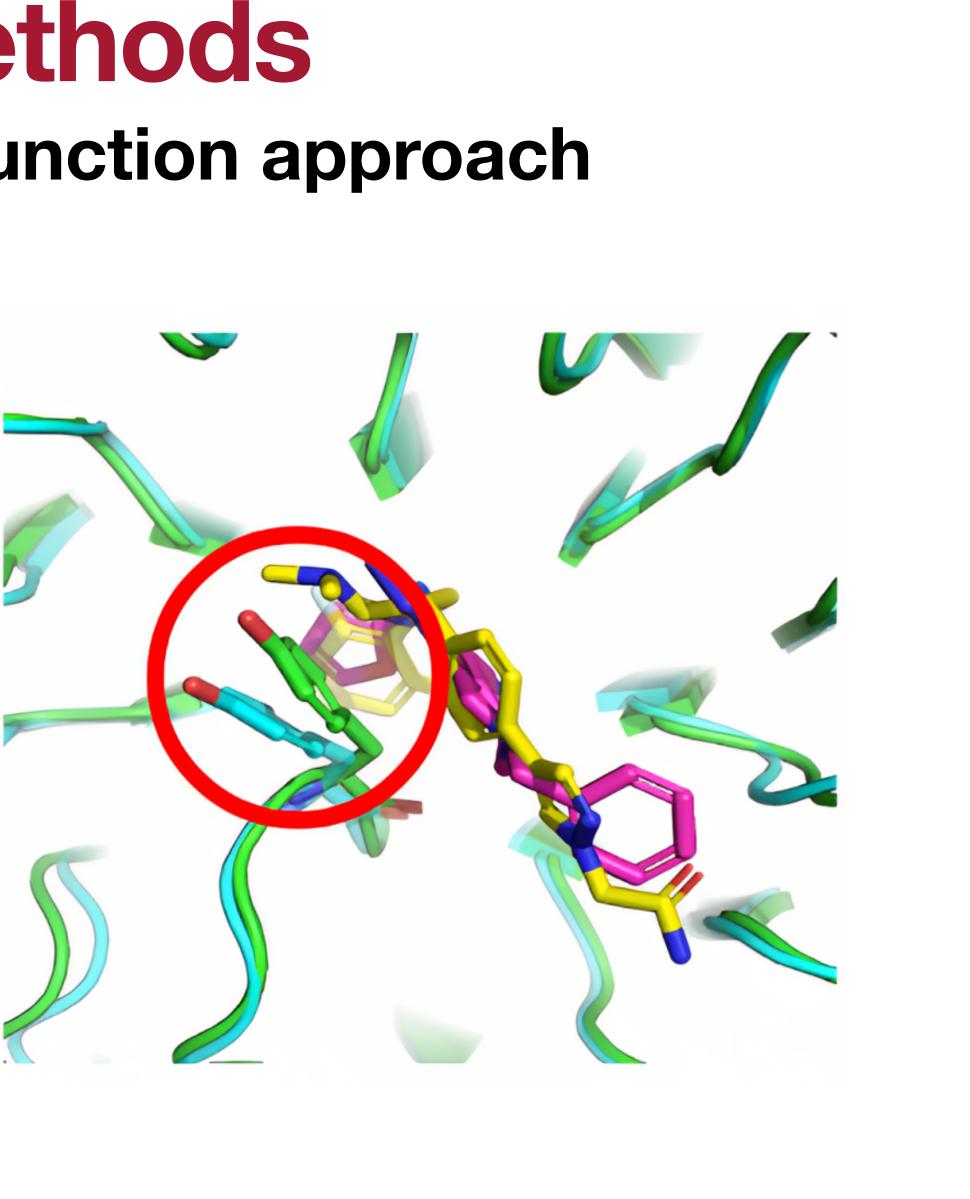
- fail to grasp with the vast search space of blind docking



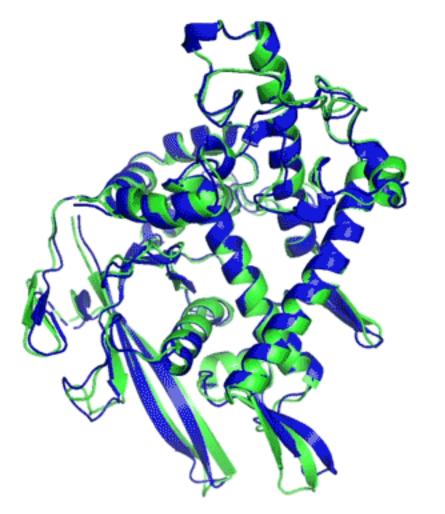


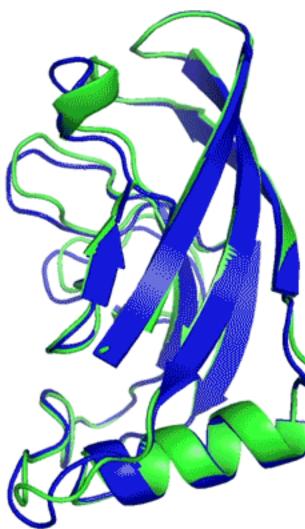


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- struggle with, e.g., side chain changes from unbound to bound protein structures



- fail to grasp with the vast search space of blind docking
- struggle with, e.g., side chain changes from unbound to bound protein structures
- unable to dock to imperfect computationally generated protein structures





T1037 / 6vr4 90.7 GDT (RNA polymerase domain) T1049 / 6y4f 93.3 GDT (adhesin tip)

Experimental result

Computational prediction



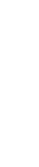












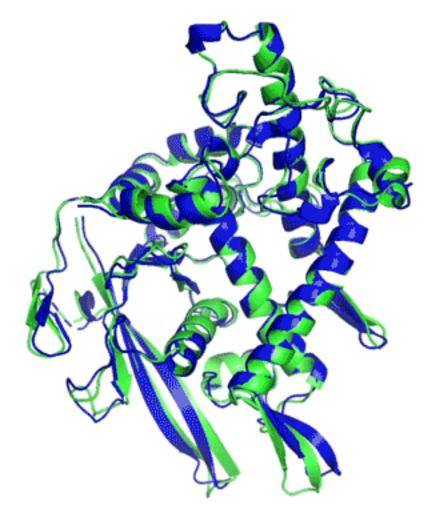


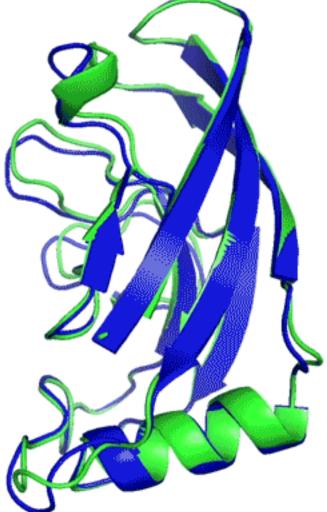
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Wong et al. "Benchmarking AlphaFold-enabled molecular docking predictions for antibiotic discovery."

Karelina et al. "How accurately can one predict drug binding modes using AlphaFold models?"







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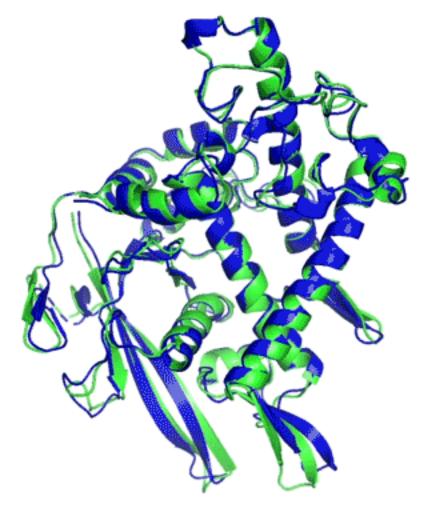


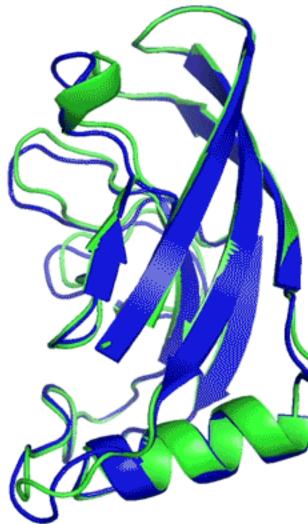




- fail to grasp with the vast search space of blind docking
- struggle with, e.g., side chain changes from unbound to bound protein structures
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### What can deep learning do for docking?



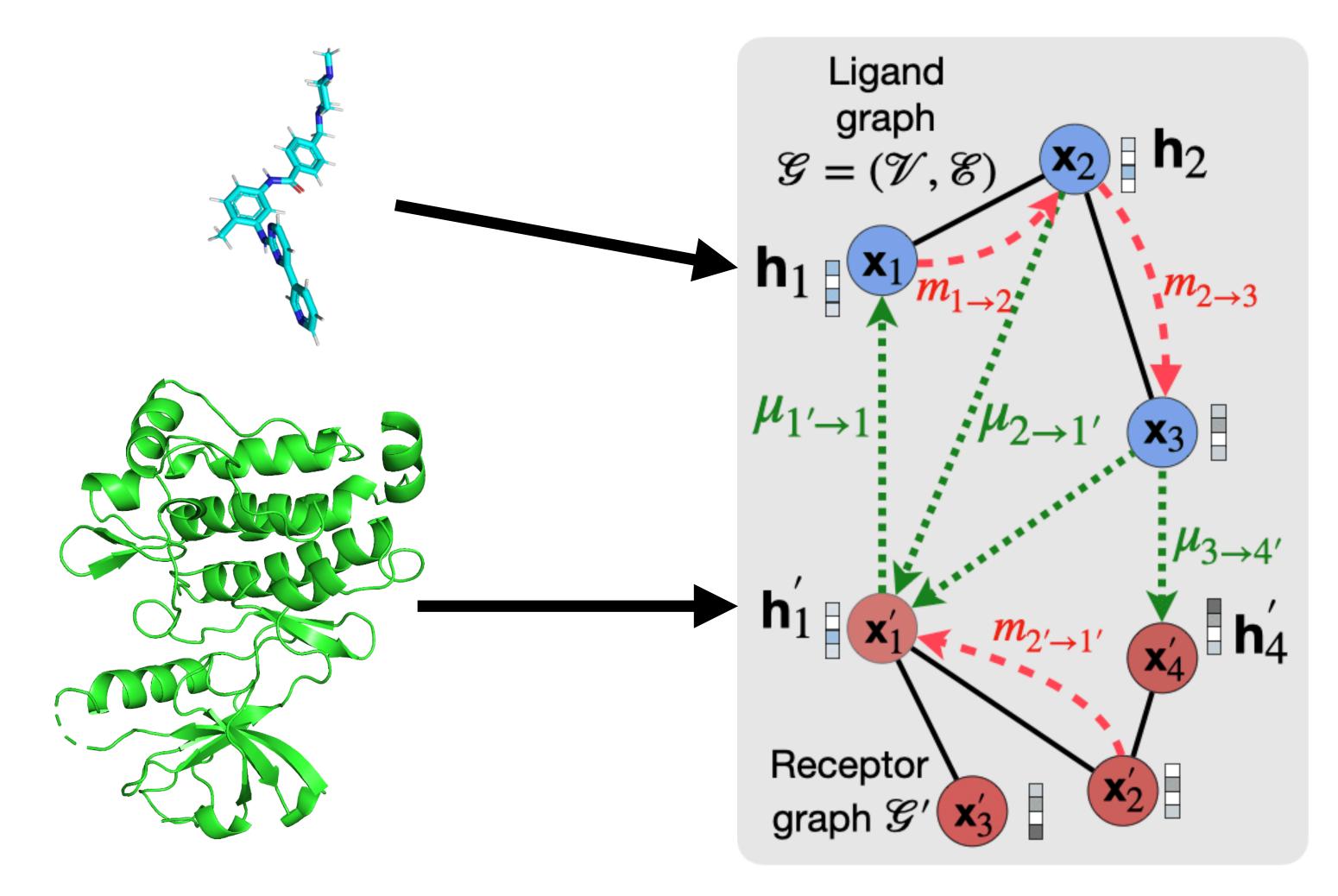


T1037 / 6vr4 90.7 GDT (RNA polymerase domain) T1049 / 6y4f 93.3 GDT (adhesin tip)

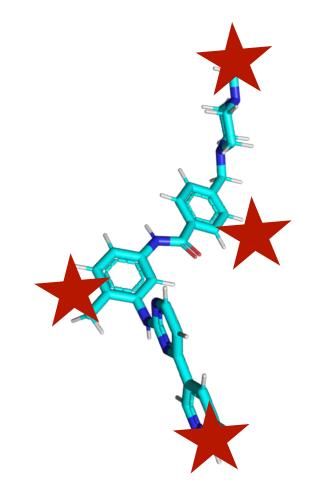
Experimental result

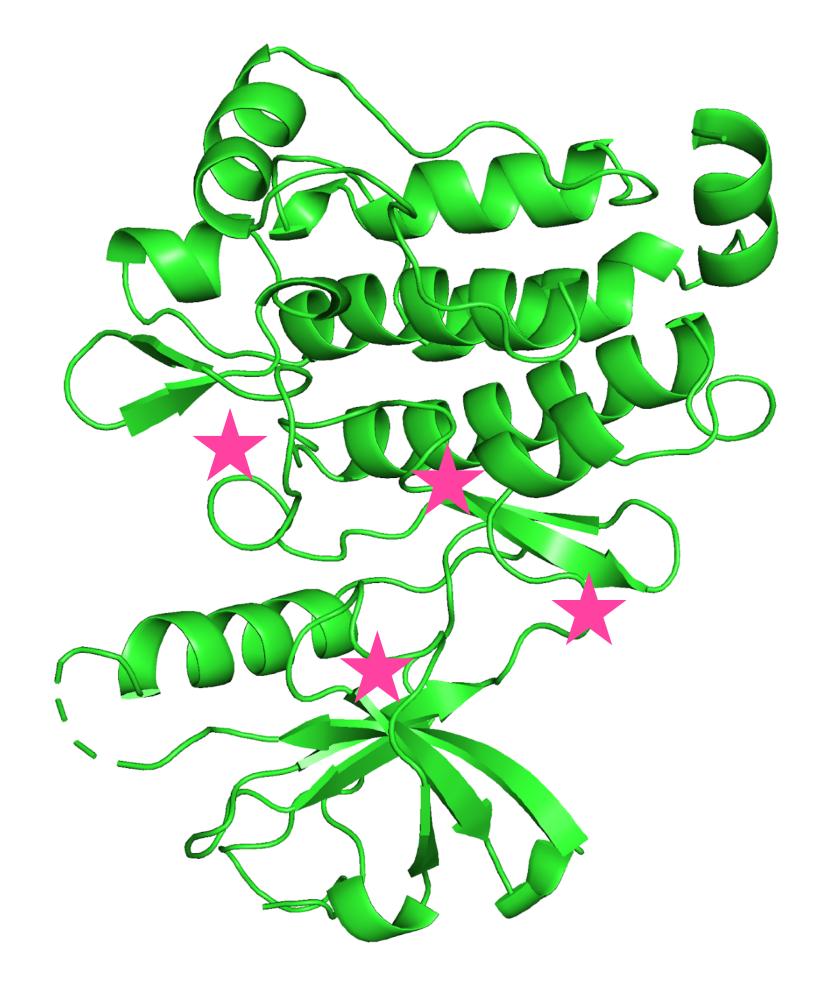
Computational prediction



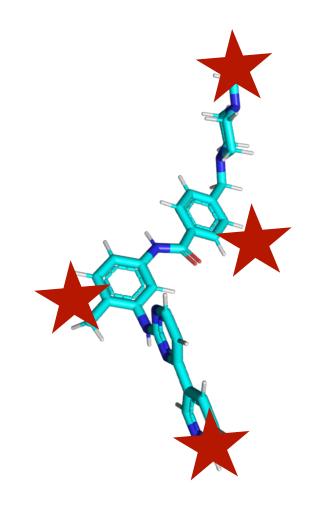






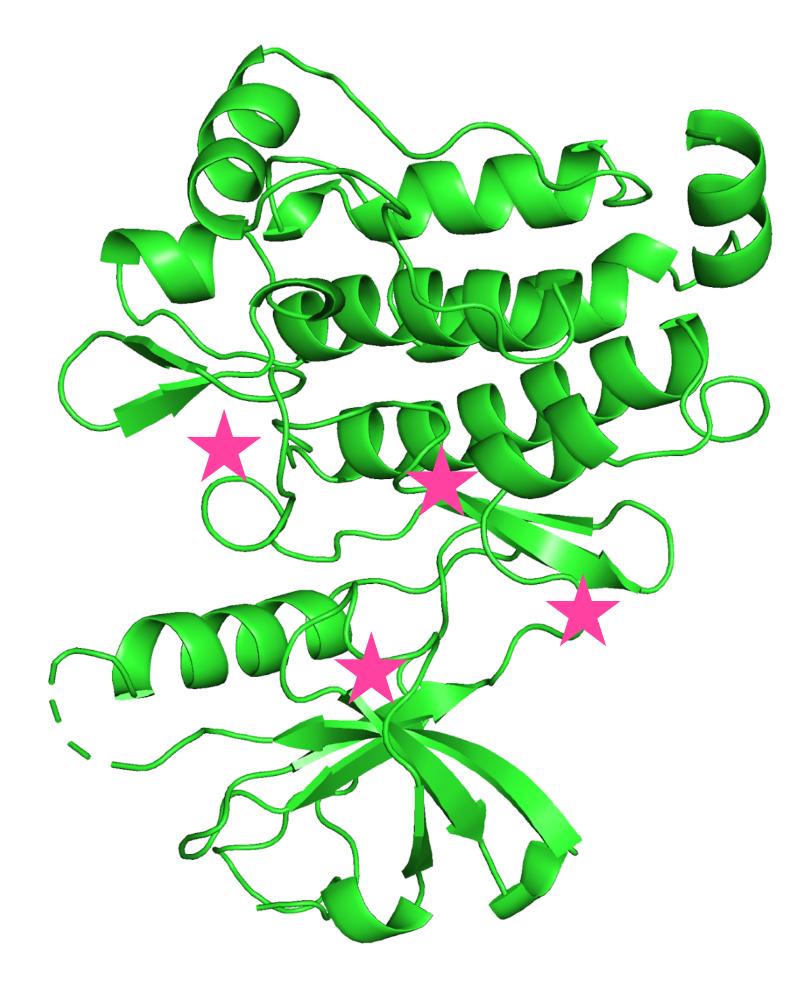


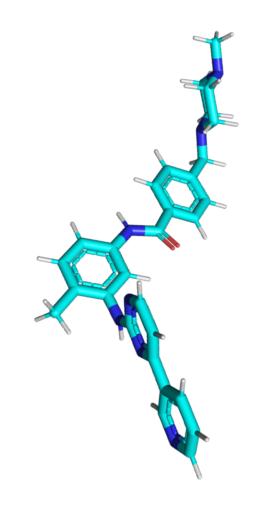




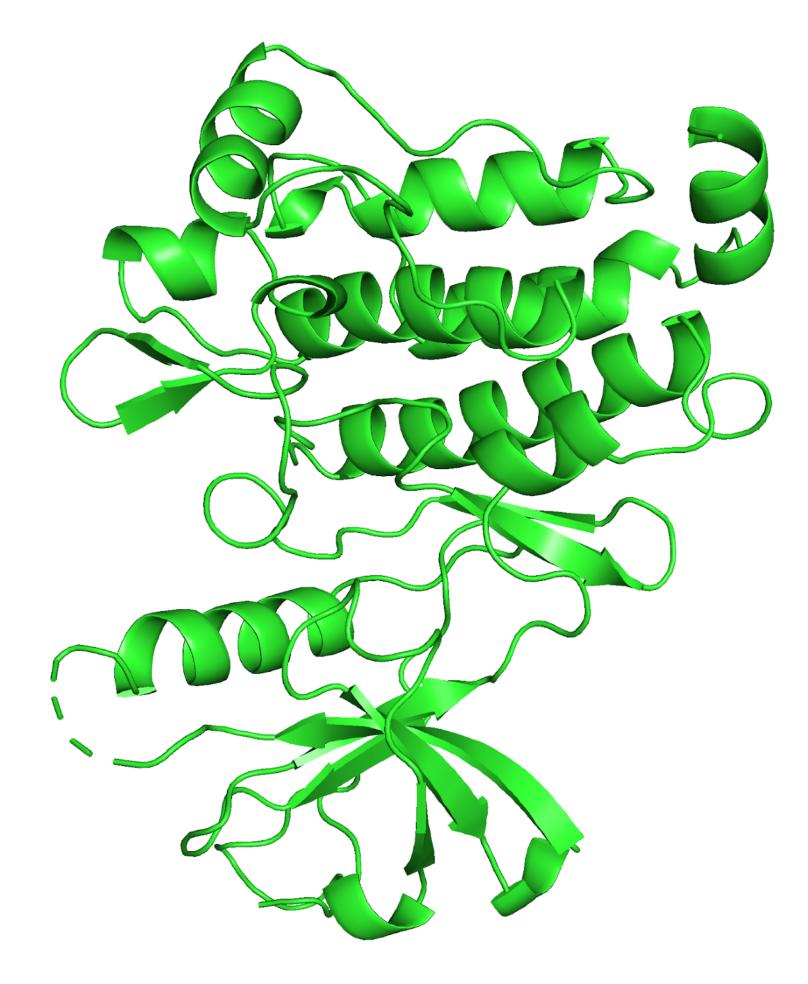
## Kabsch algorithm calculates rototranslation to match keypoints

(EquiDock) Ganea et al. 2021, Independent SE(3)-Equivariant Models for End-to-End Rigid Protein Docking

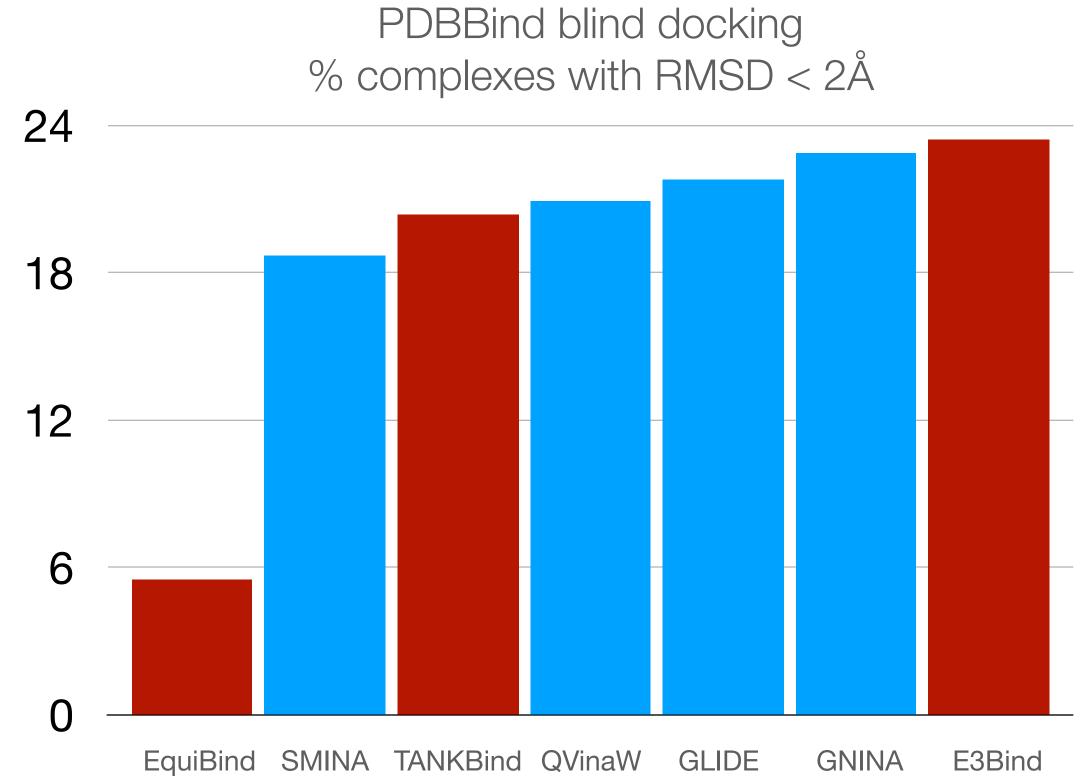




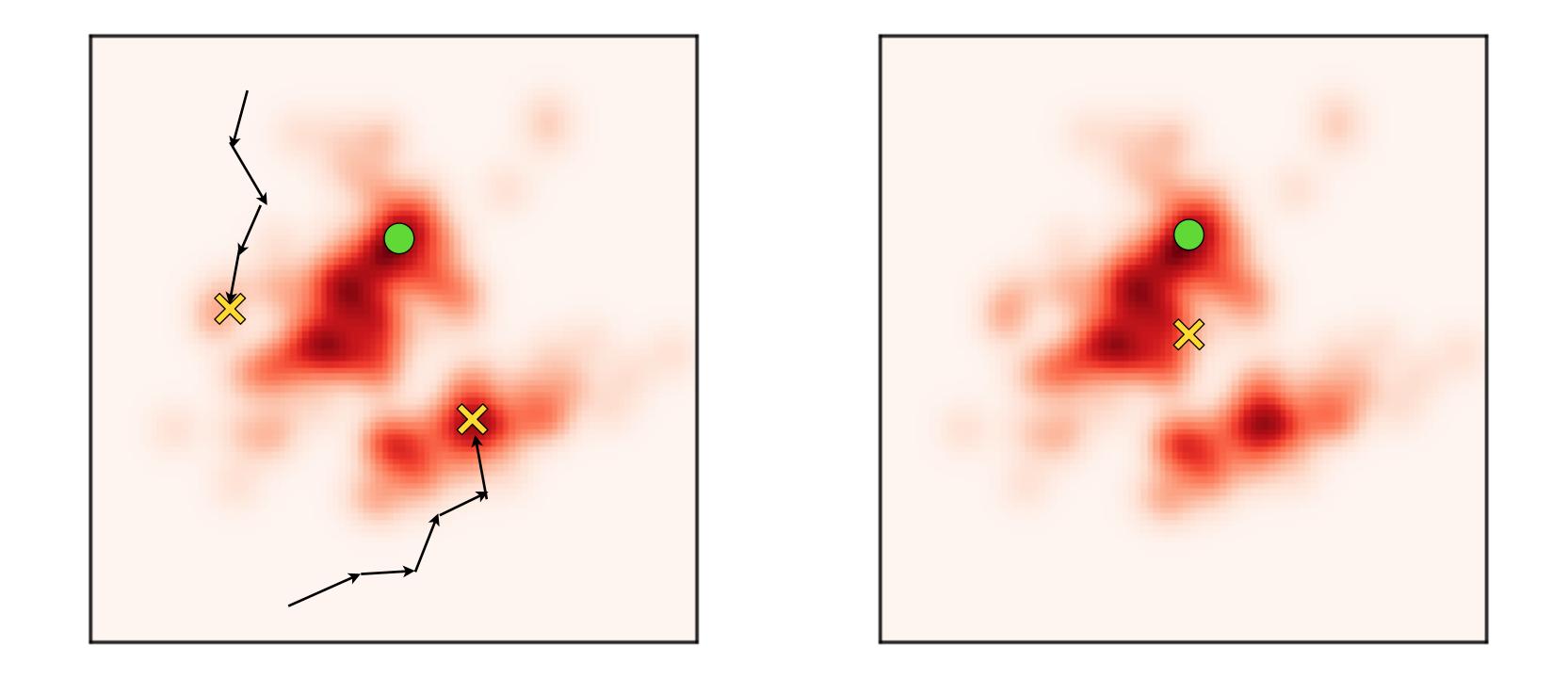
## Apply rototranslation to molecule coordinates



## **Previous DL approaches** No meaningful advances of SOTA.



# Approaches to docking recap



Traditional docking: sampling & optimization over scoring function: **no finite-time guarantees**!

Previous deep learning: poor-quality single prediction with no refinement

# **Docking as a Generative Modeling Problem** A key paradigm shift from prior deep learning approaches

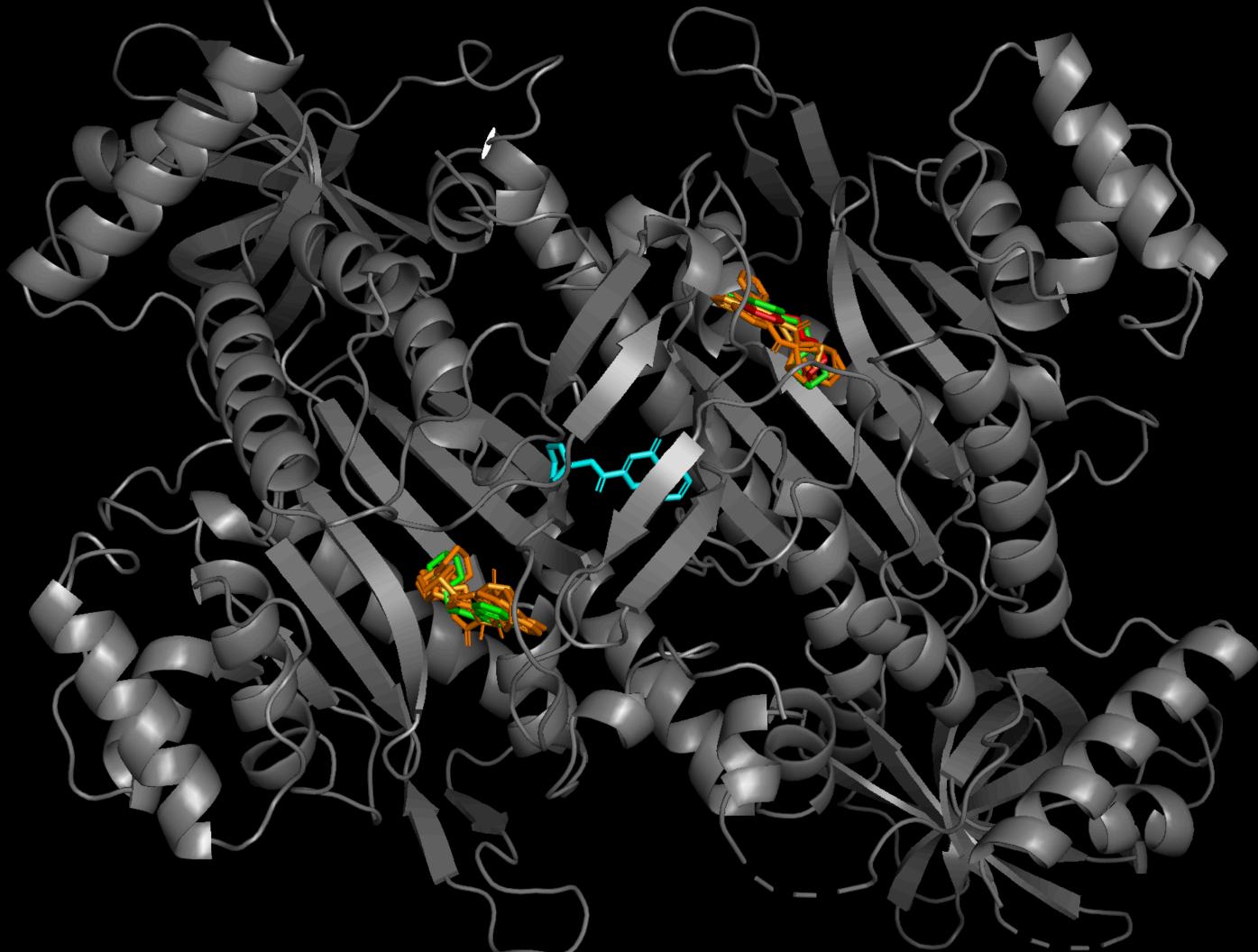
- Docking has significant aleatoric and epistemic uncertainty
- Any method will exhibit uncertainty about correct pose between multiple alternatives
- Regression methods to minimize squared error predict (weighted) mean
- Generative model will populate all/most modes

True bound structure **Regression** prediction Generative samples X ×

Docking energy landscape



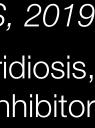
# **Regression vs Generation for Docking** Aleatoric uncertainty induces "averaging" effect



## **Crystal Structure EquiBind (regression) Generative samples DiffDock top-1**

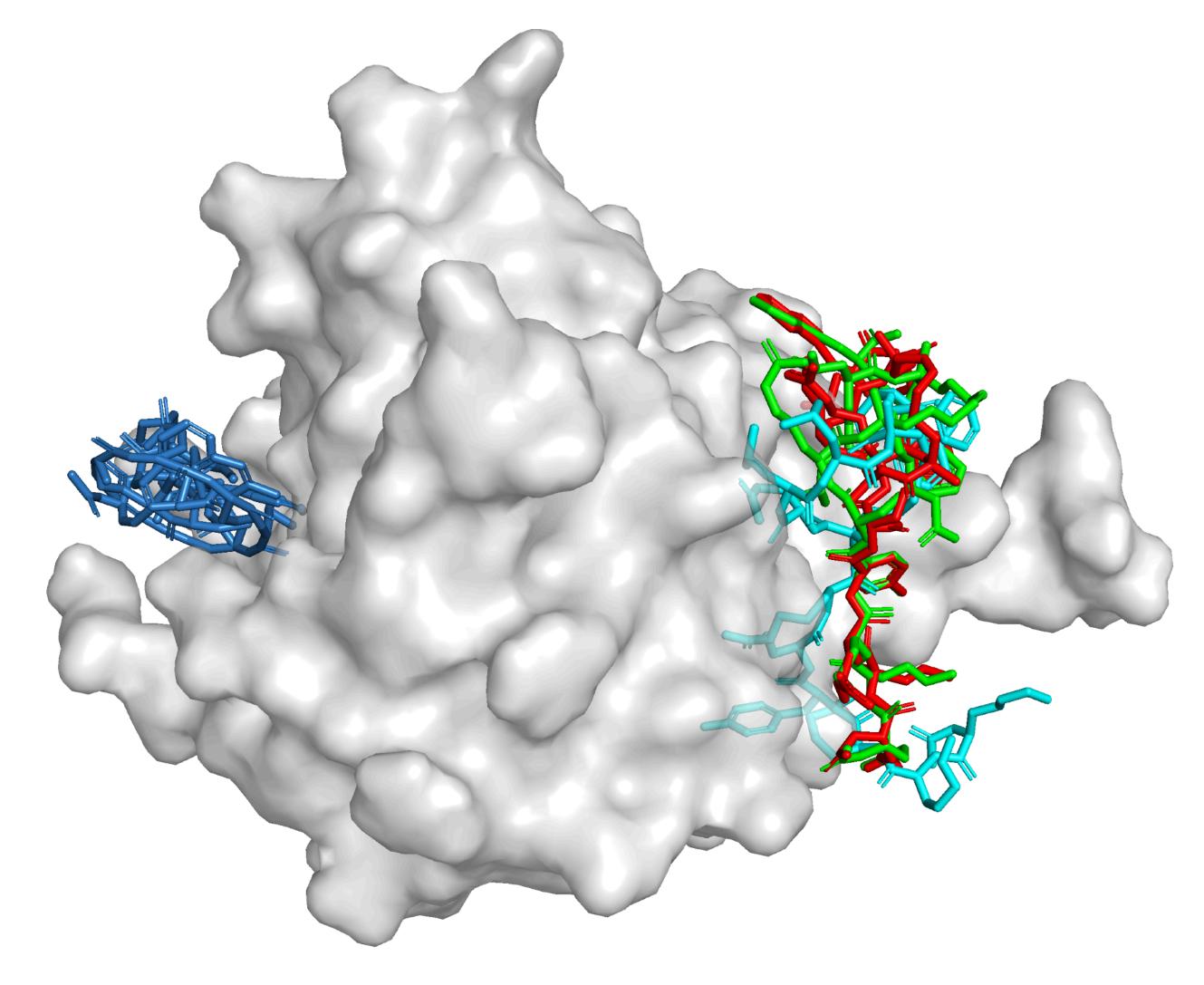
Baragaña et al. PNAS, 2019

PfKRS, drug target in malaria and cryptosporidiosis, complexed with chromone inhibitor





## **Regression vs Generation for Docking** Model uncertainty is another issue



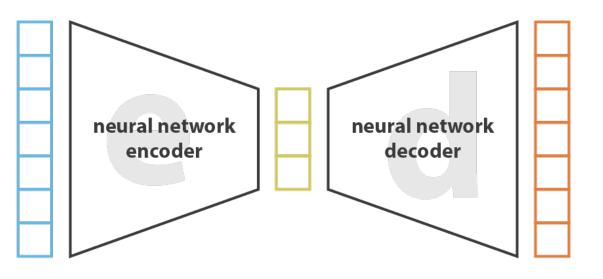
### **Crystal Structure EquiBind (regression) TANKBind (regression) DiffDock top-1**



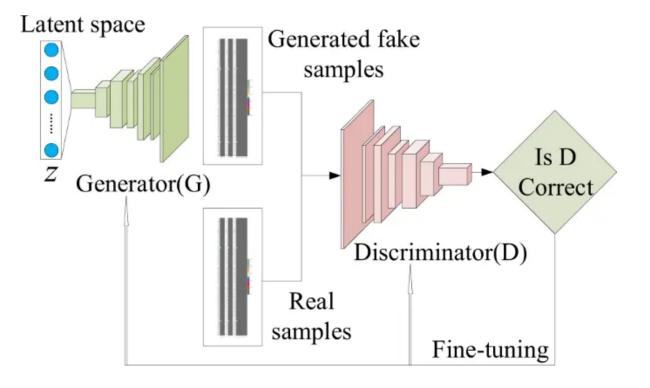
# A Generative Model for Molecular Docking

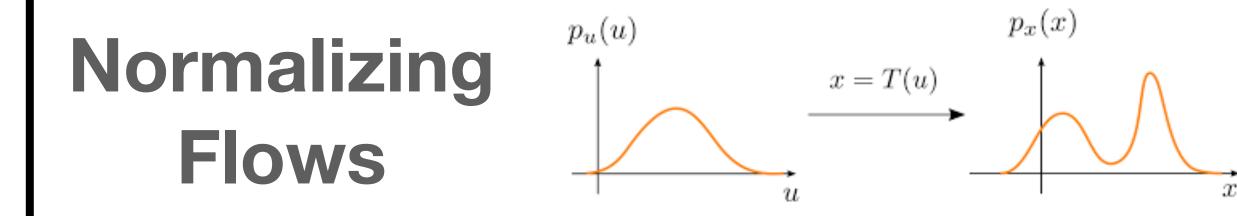
## How to make our Generative Model? ML has developed plenty of options

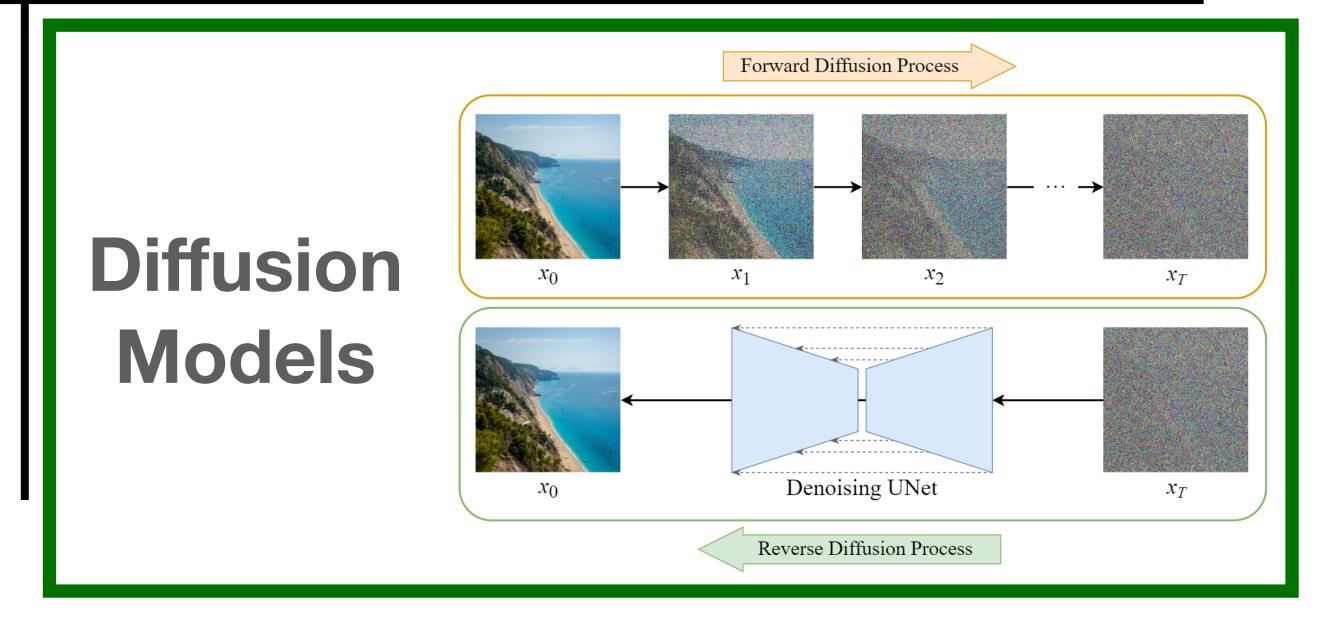
## Variational Autoencoders



## Generative Adversarial Networks







# **Diffusion Generative Models**







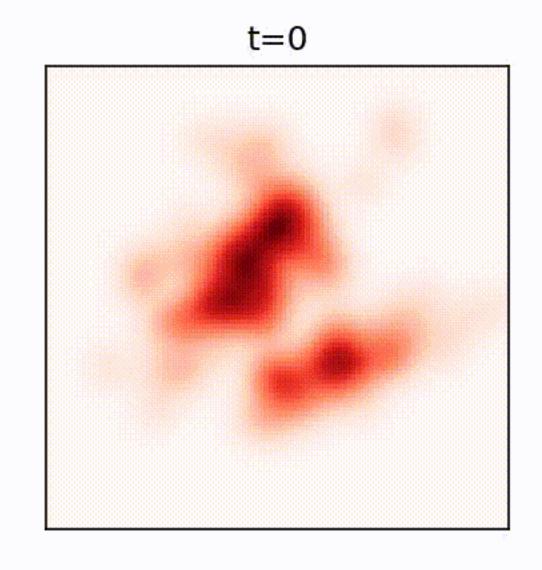


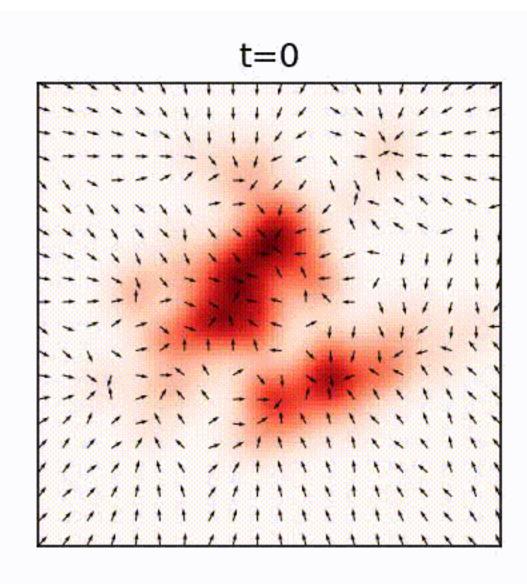






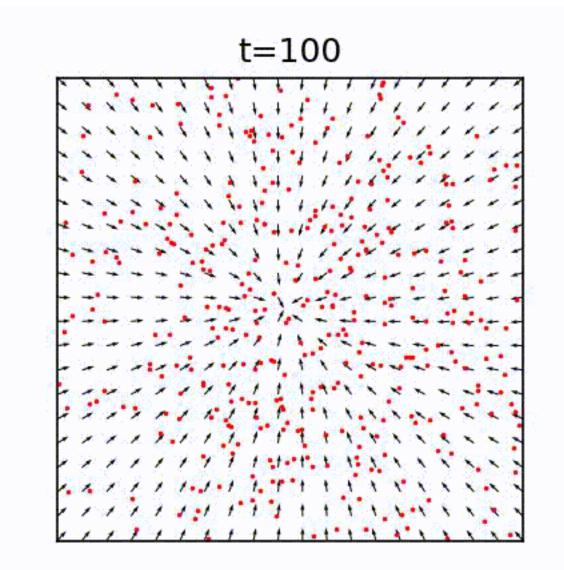
# **Diffusion Generative Models**





Define the **forward diffusion**  $d\mathbf{x} = f(\mathbf{x}, t) dt + g(t) d\mathbf{w}$ 

Learn the score (gradient of the log density) of the evolving data distribution



 $\mathbf{s}_{\theta}(\mathbf{x}, t) \approx \nabla_{\mathbf{x}} \log p_t(\mathbf{x})$ 

Sample the **reverse diffusion**  $d\mathbf{x} = [f(t) - g^2(t) \mathbf{s}_{\theta}(\mathbf{x}, t)] dt + g(t) d\mathbf{w}$ 

[Andersen '82; Song et al '21] 26



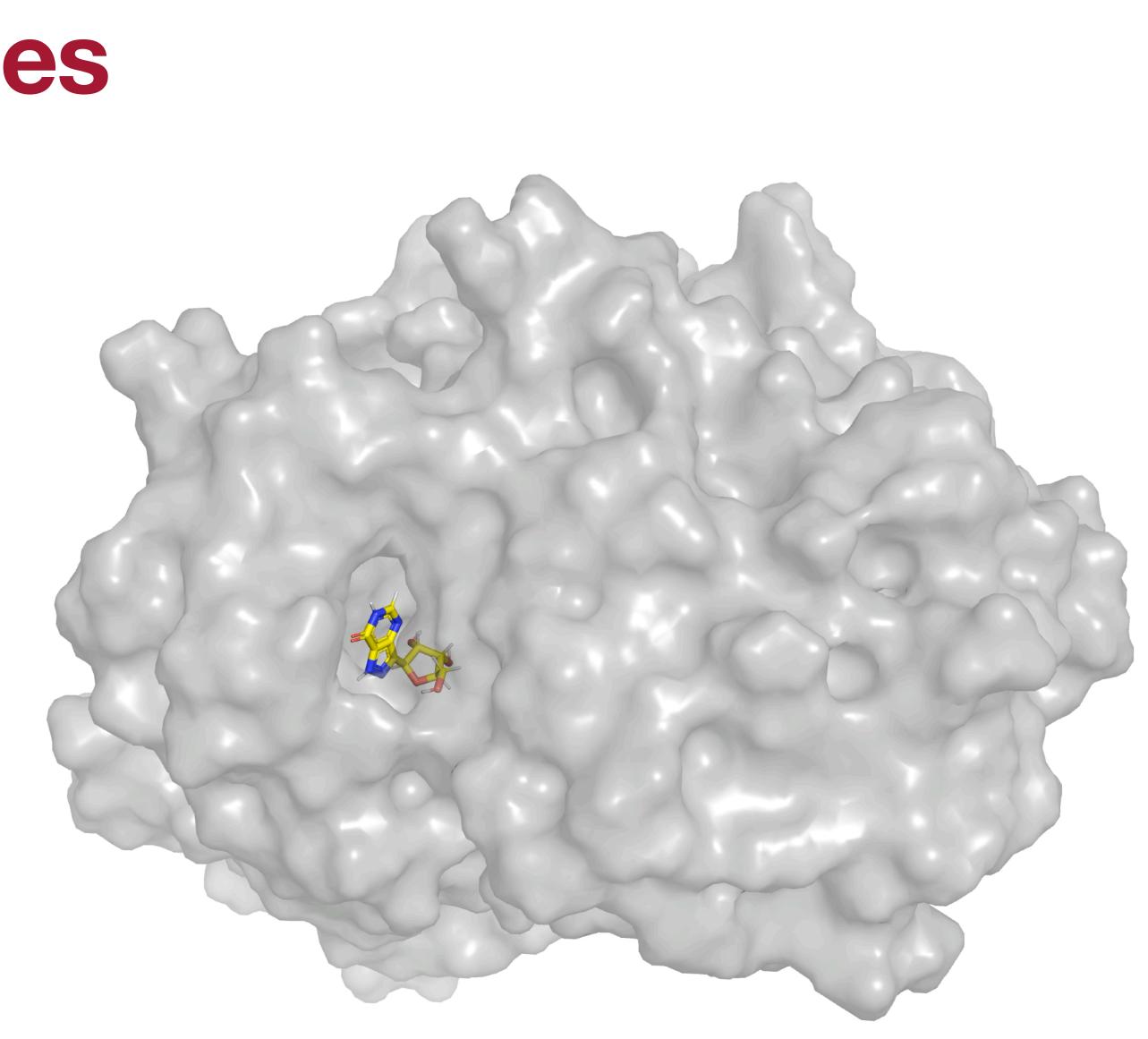




# Space of Ligand Poses

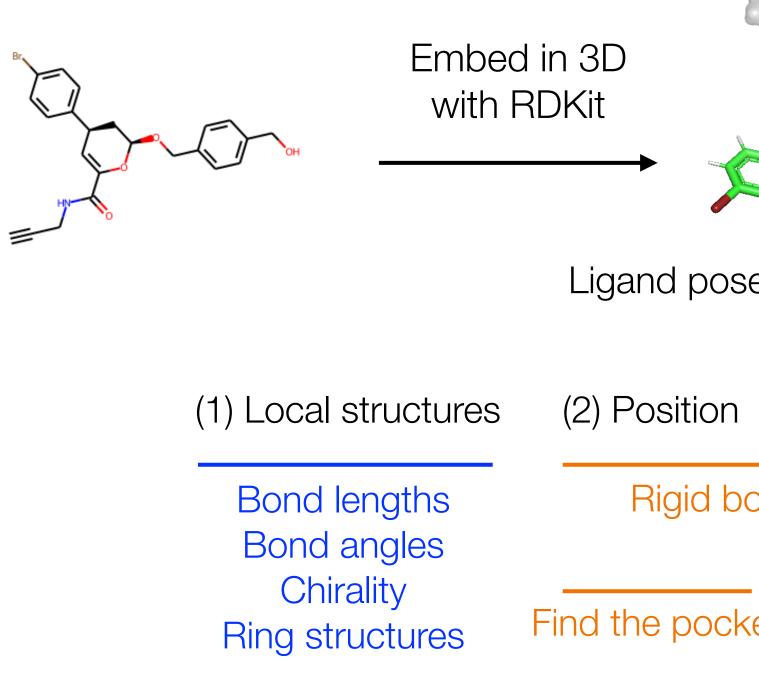
A ligand's pose technically is  $L \in \mathbb{R}^{3n}$ 

...but docking involves far fewer degrees of freedom

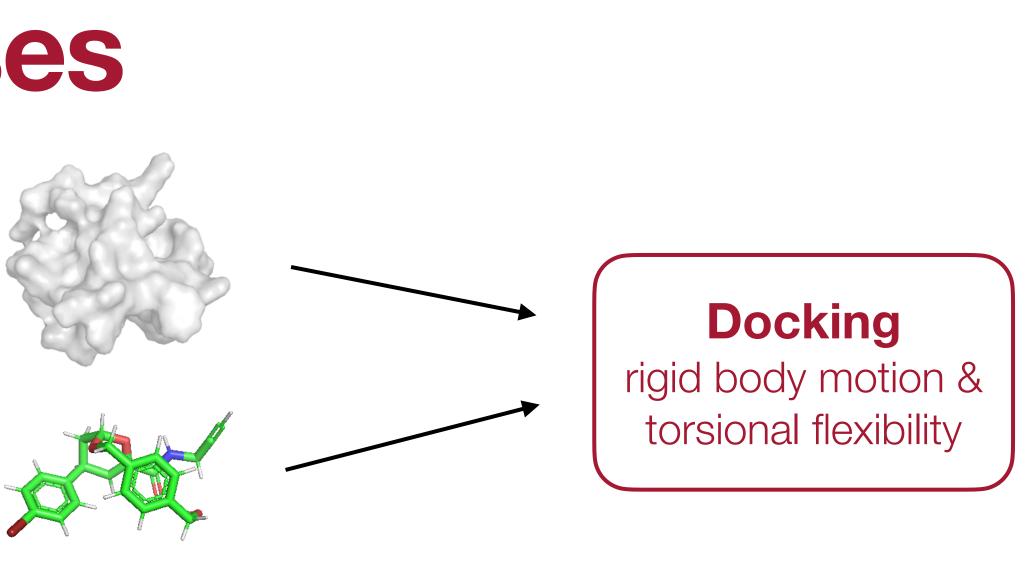




# **Space of Ligand Poses**



## Keep local structures fixed: diffuse over m+6 dim. submanifold

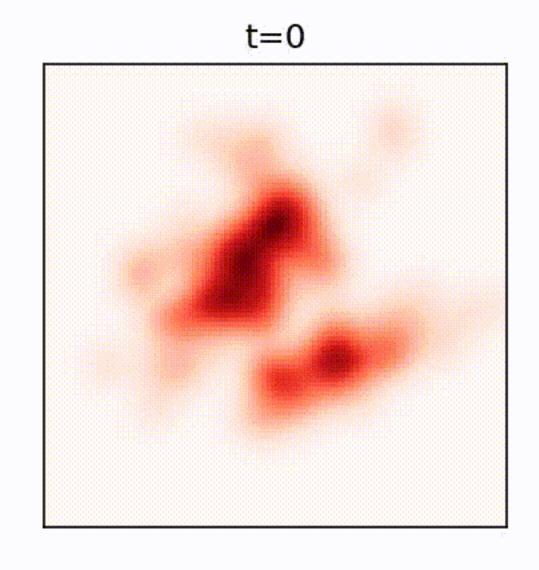


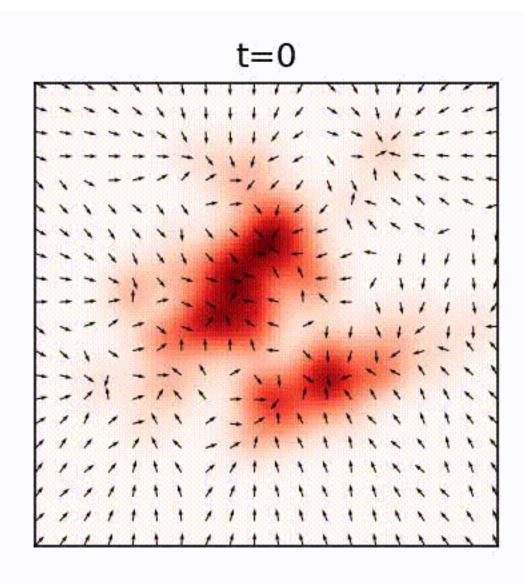
Ligand pose described by

ion	(3) Orientation	(4) Torsion angles			
d bod	ly motion	Torsional flexibility			
ocket	Fit in	Fit in the pocket			



# **Diffusion Generative Models**



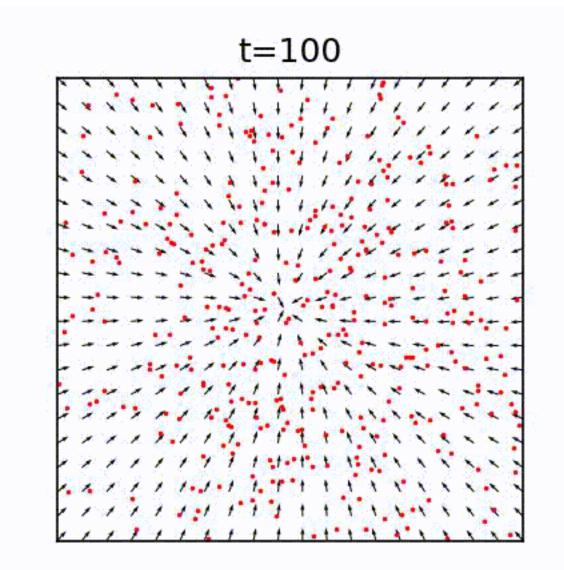


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[Andersen '82; Song et al '21] 30







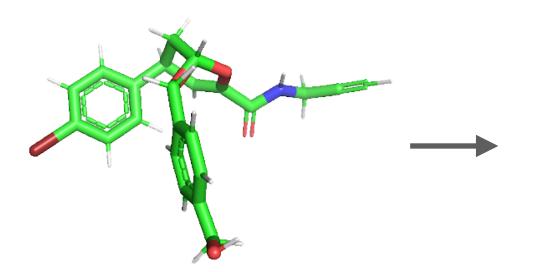
# **Mapping to the Product Space**

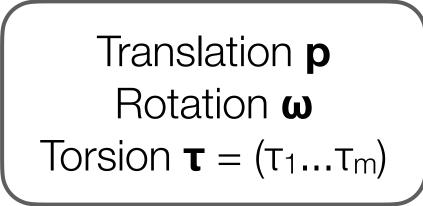
Point on ligand pose manifold "parameterized" by:

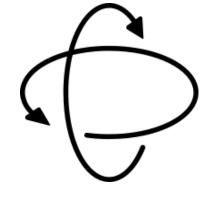
Position  $\in \mathbb{R}^3$ Orientation  $\in SO(3)$ Torsions  $\in \mathbb{T}^m$ 

"Diffeomorphic" to product space  $\mathbb{R}^3 \times SO(3) \times \mathbb{T}^m$ 

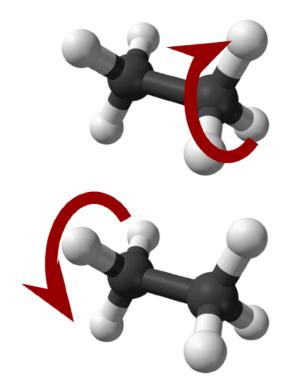
Need to map **displacements** on the product space to **changes** of pose.







### **Rotation:** around center of mass



#### **Torsion:**

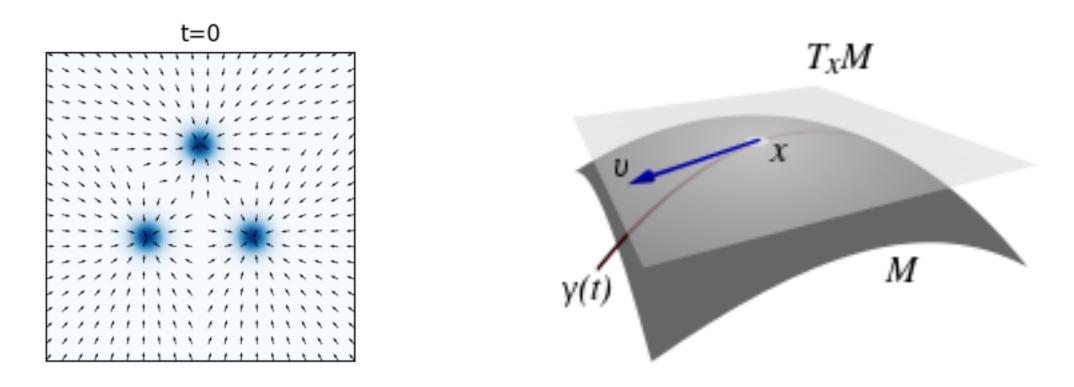
post-torsion RMSD alignment  $\rightarrow$  no linear or angular momentum





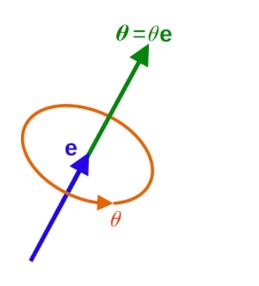
# **Product Space Diffusion**

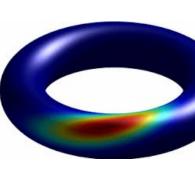
Diffusion generative modeling works on manifolds [de Bortoli et al, '22] ...provided the score model predicts in the **tangent space** 



...and that we can:

- 1. sample the heat kernel for arbitrary t
- 2. compute its score
- 3. sample from the stationary distribution (t = T)





	Space	$\mathbb{R}^3$ (position)	SO(3) (orientations)	$\mathbb{T}^m$ (torsion angles)
	Tangent space	R <sup>3</sup> (translation vectors)	$\mathbb{R}^3$ (rotation vectors)	$\mathbb{R}^m$ (torsion updates
	Heat kernel	Normal	IGSO(3)	Wrapped normal
	Stationary dist.	Normal	Uniform	Uniform
	SE(3) symmetry	Equivariant	Equivariant	Invariant
		Steps	Turns	Twists



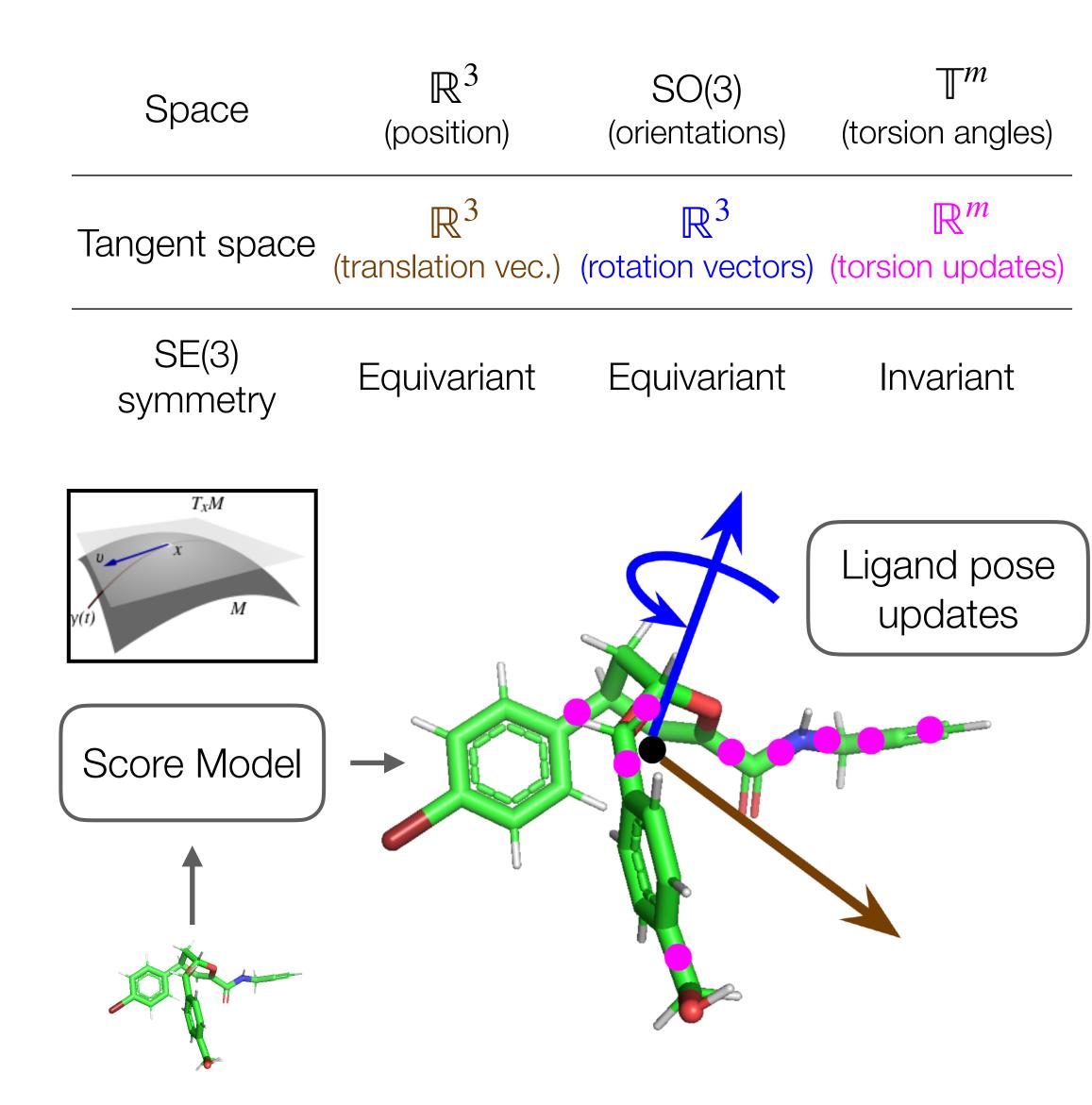
5)

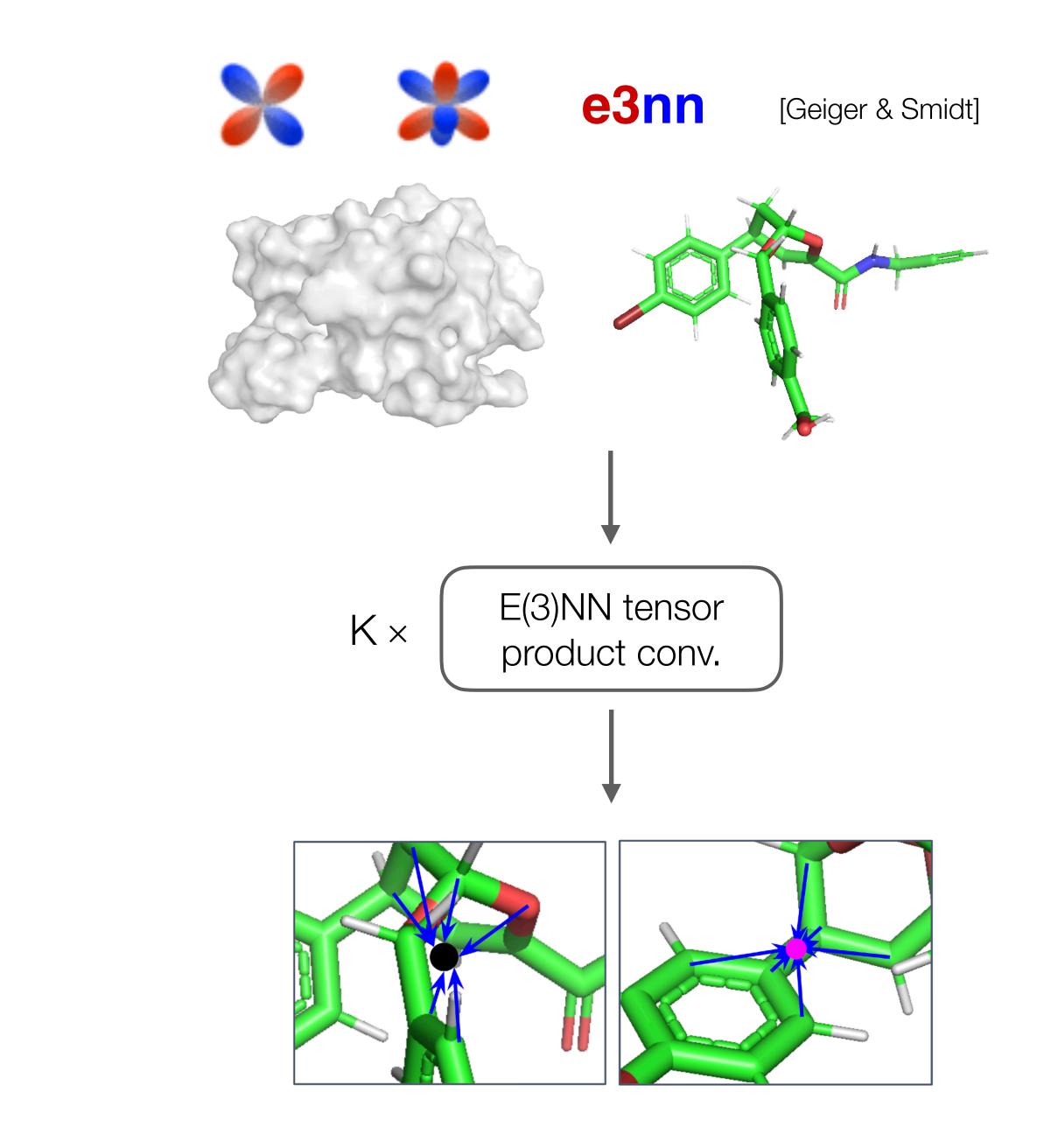
es)





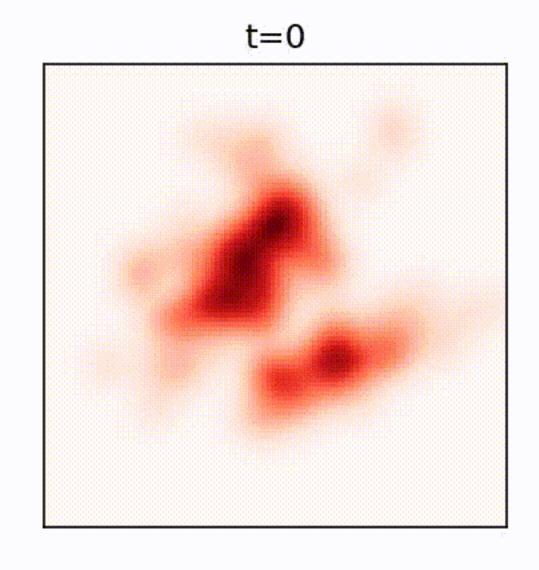
# Score Model

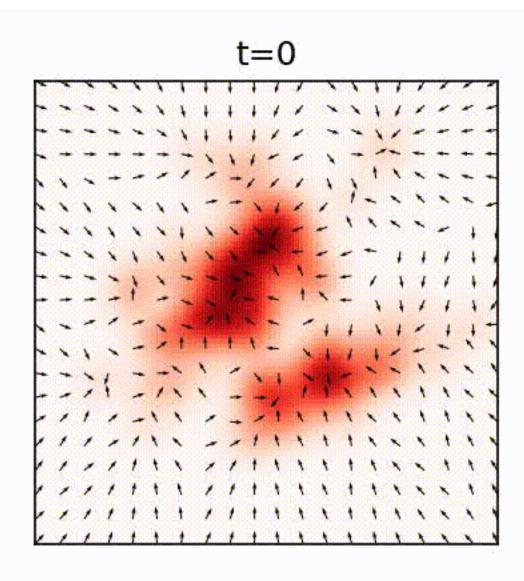






# **Diffusion Generative Models**



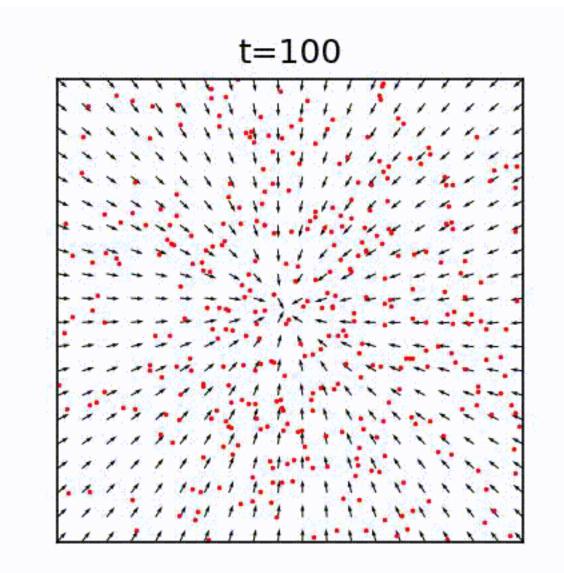


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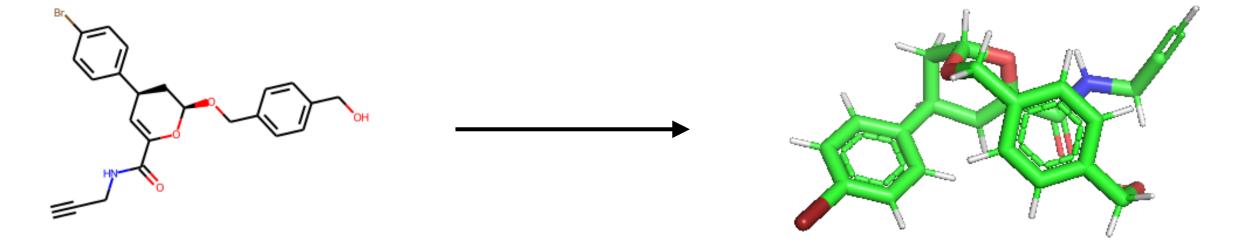
[Andersen '82; Song et al '21] 41





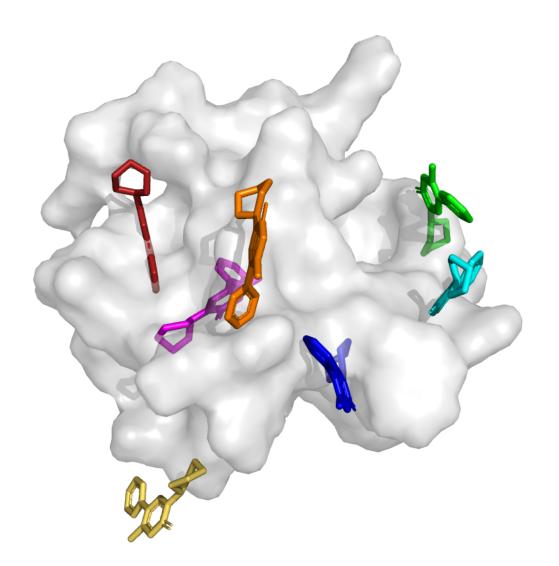
## 1. Embed with RDKit

- 2. Sample N random poses
- 3. Simulate reverse diffusion
- 4. Rank and select top M poses





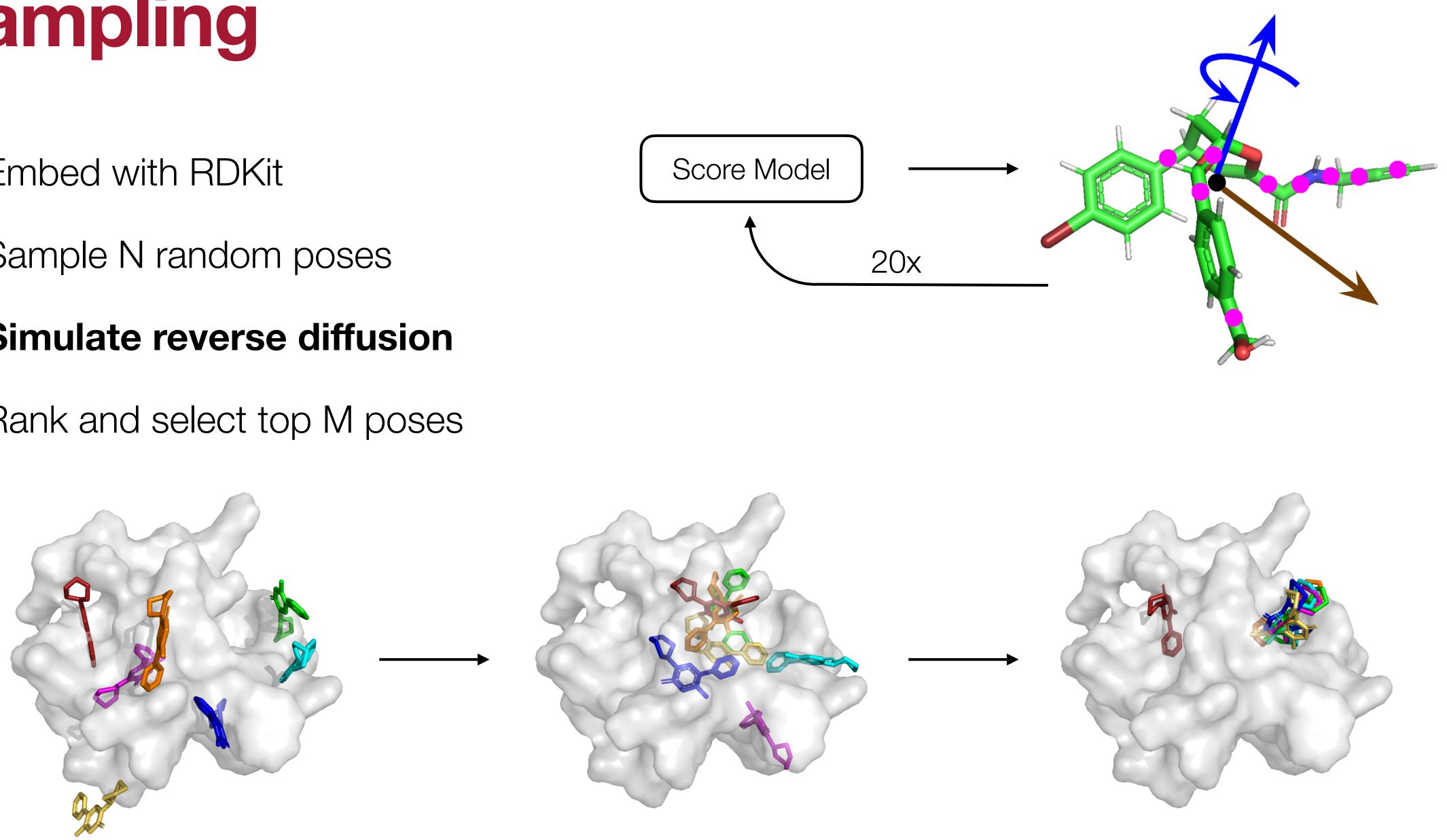
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Space	$\mathbb{R}^3$ (position)	SO(3) (orientations)	$\mathbb{T}^m$ (torsion angles)
Stationary distribution	Normal	Uniform	Uniform



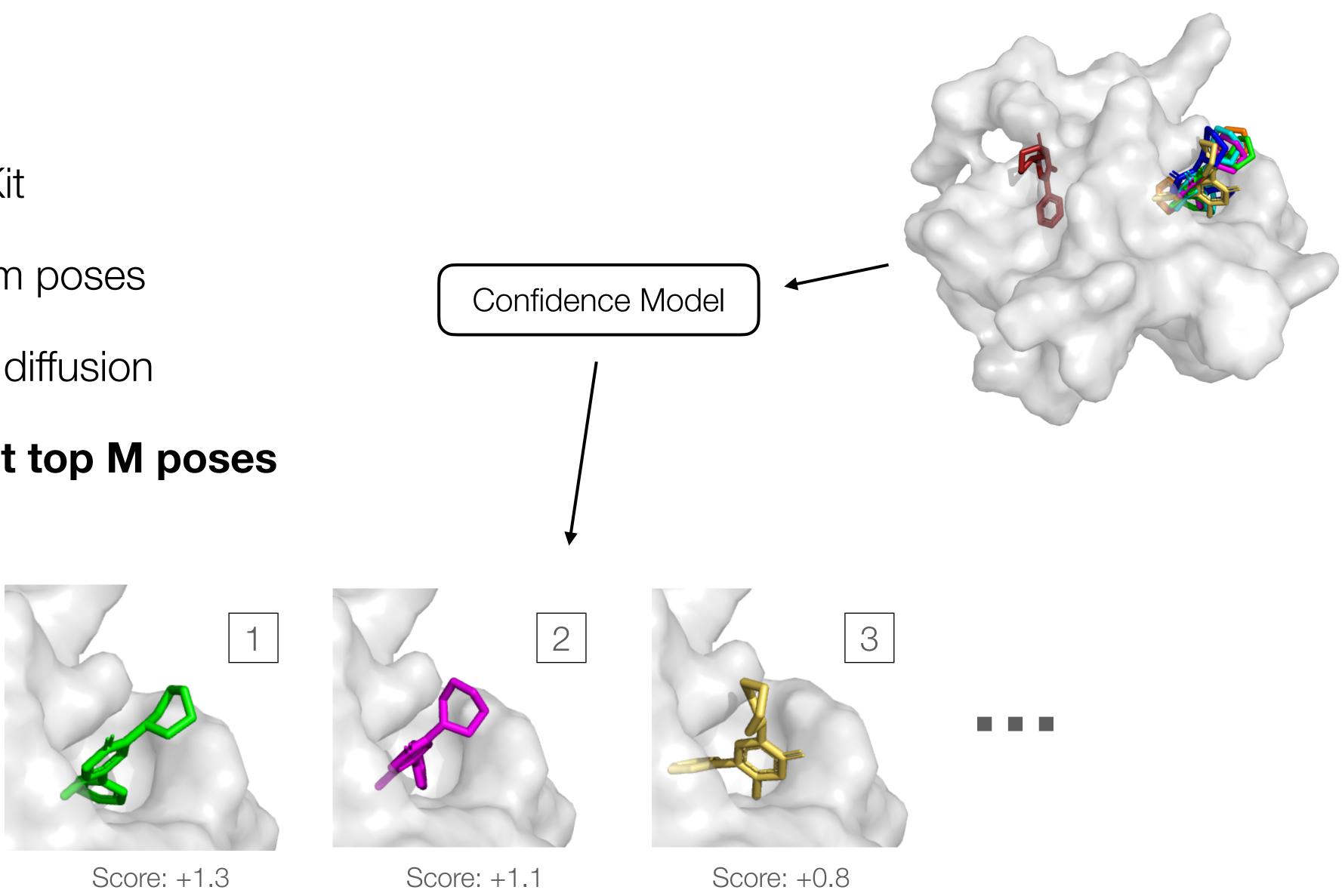
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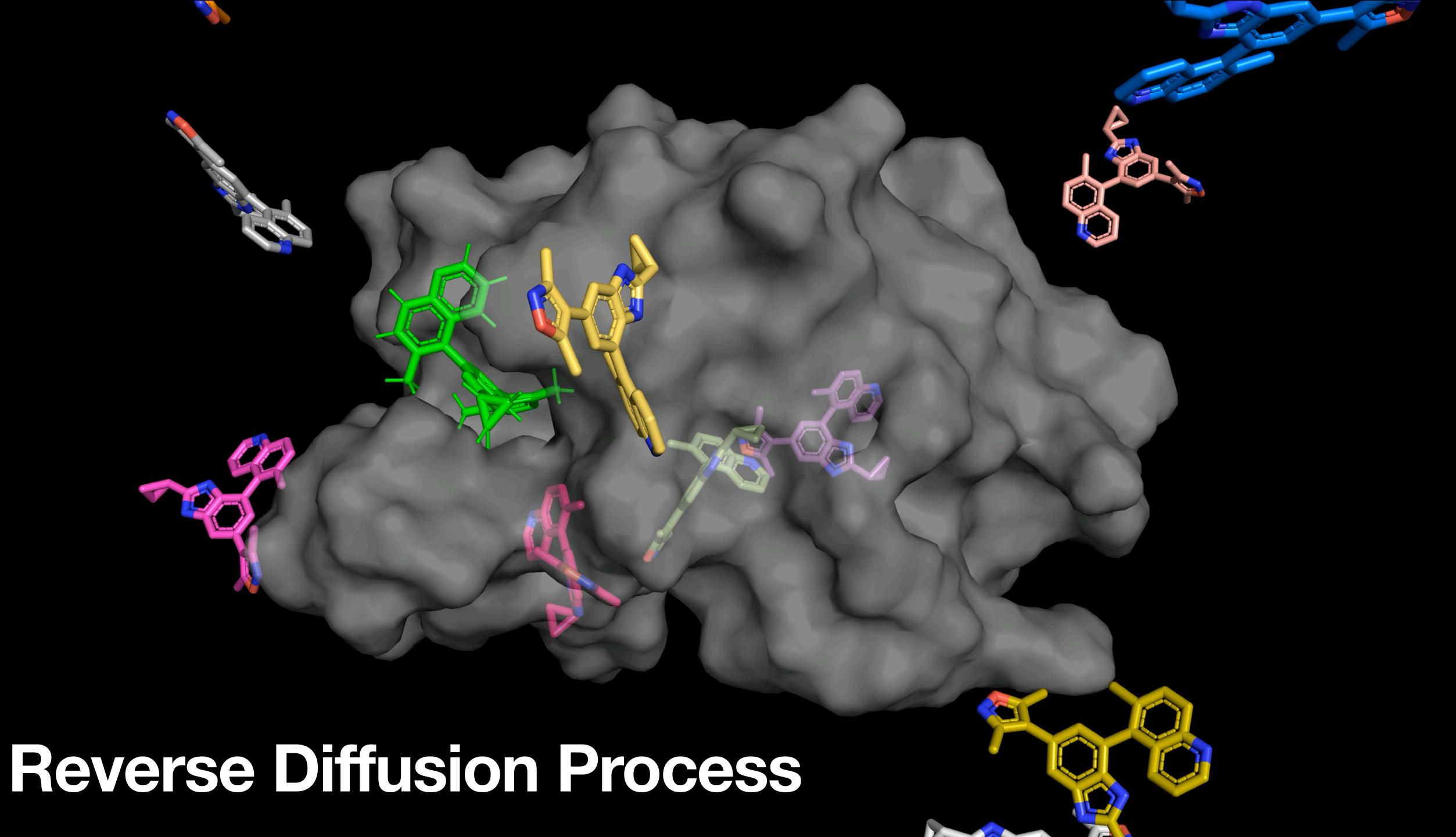


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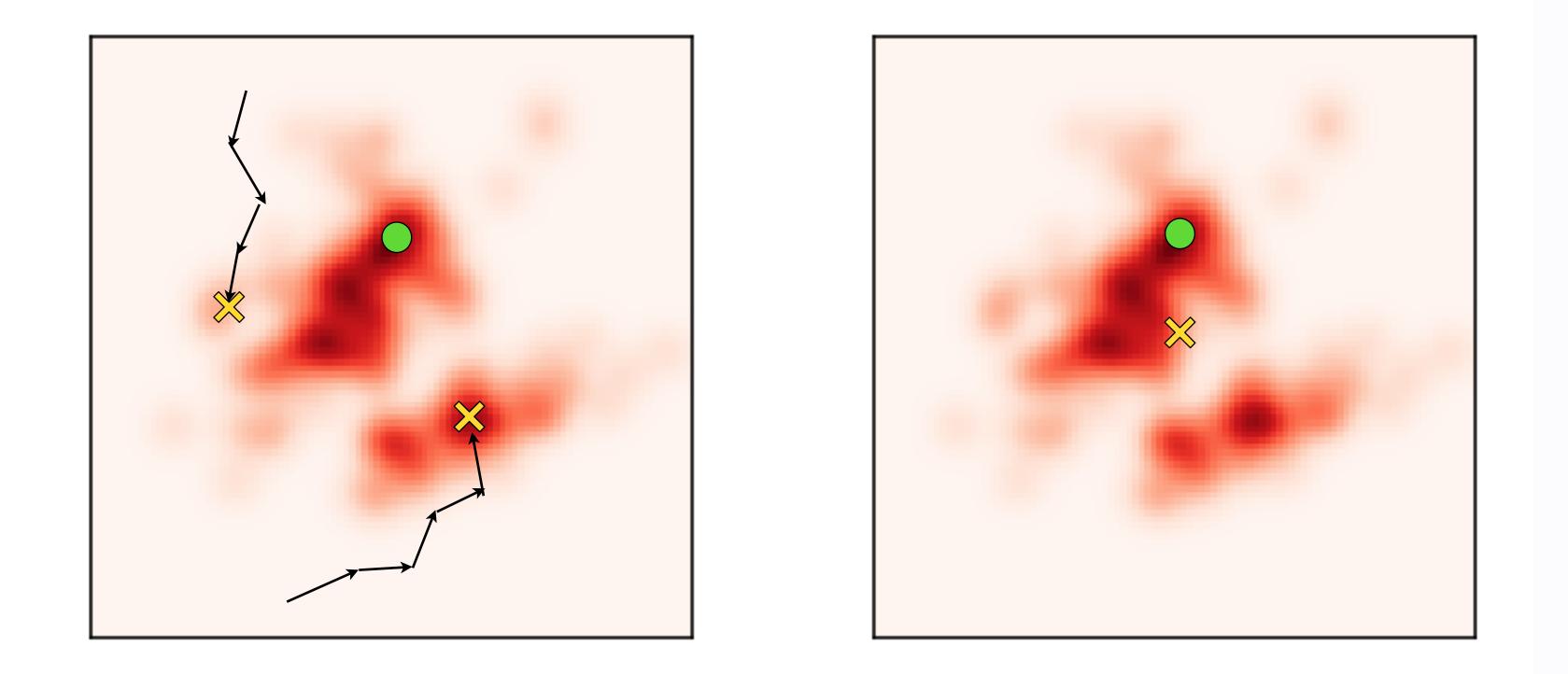
## 4. Rank and select top M poses







# Approaches to docking recap



Traditional docking: sampling & optimization over scoring function: no finite-time guarantees!

Previous deep learning: poor-quality single prediction and no refinement

XXXXXXXXXXXXXXXXX //////////XXXXXXXXX ATTETTTTTTTTANANNY 1 1-1 4 1-1-1 1 1 1 1 1 1 1 1 1

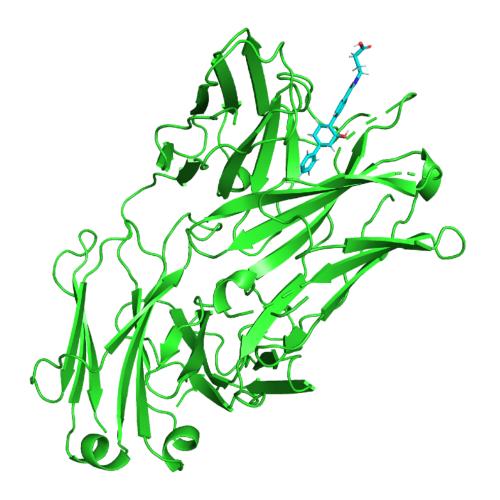
**Diffusion:** sample from nonconvex density in finite time via a time-evolving vector field

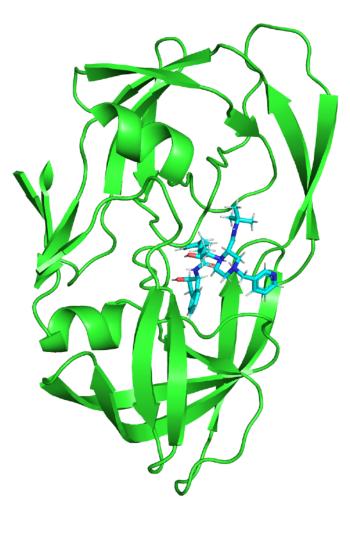




# Standard benchmark PDBBind

19k experimentally determined structures of small molecules + proteins





# **Baselines: search-based and deep learning**



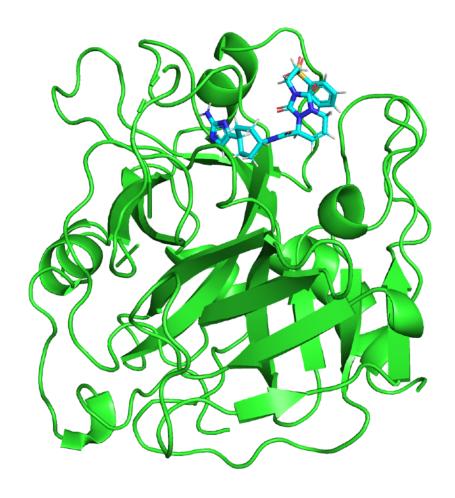
McNutt et al. 2021

**SMINA** 

Koes et al. 2013

### QuickVina-W

Hassan et al. 2017





Schrödinger. Release 2021-4

## EquiBind

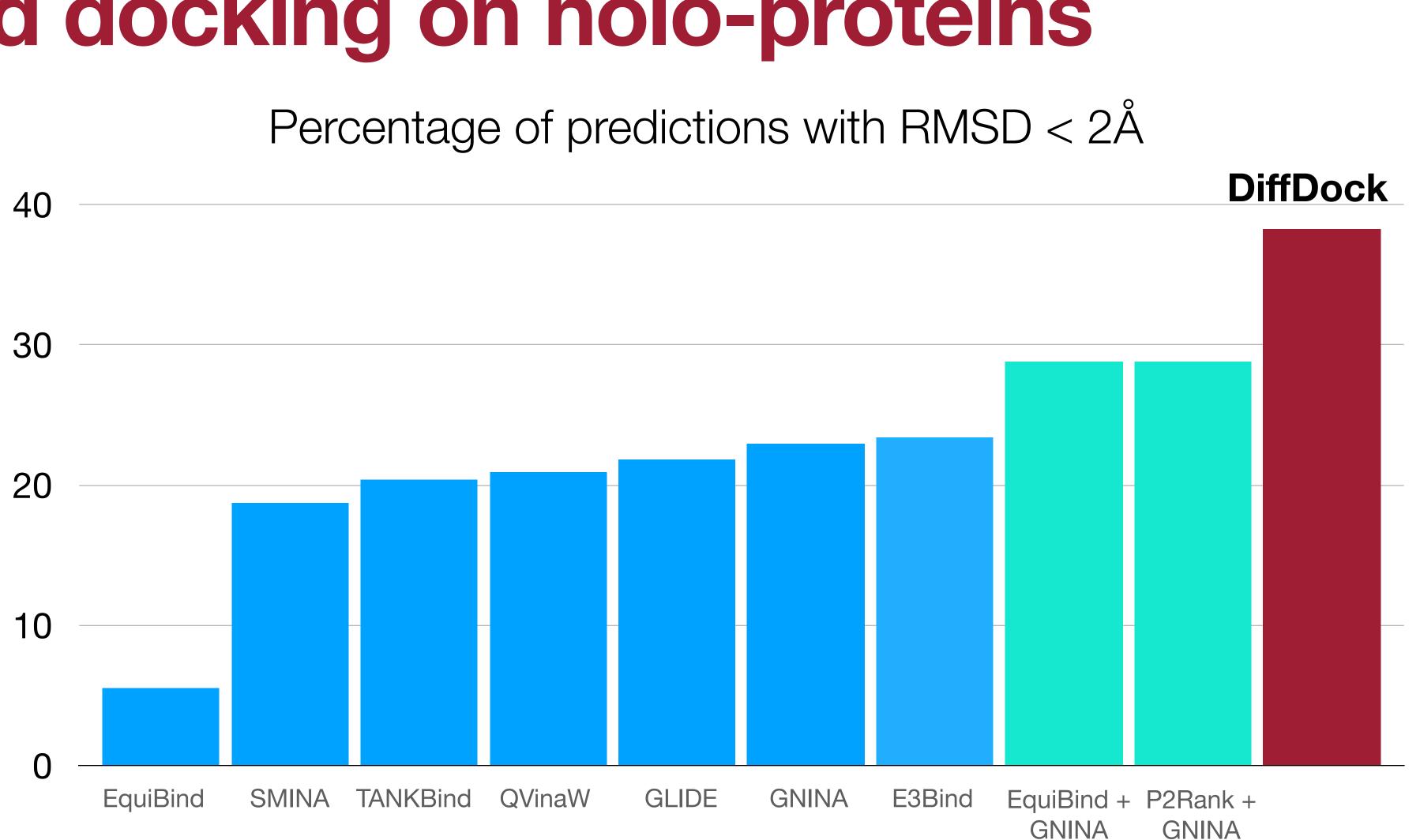
Stärk et al. 2022

### TankBind

Lu et al. 2022



# Blind docking on holo-proteins

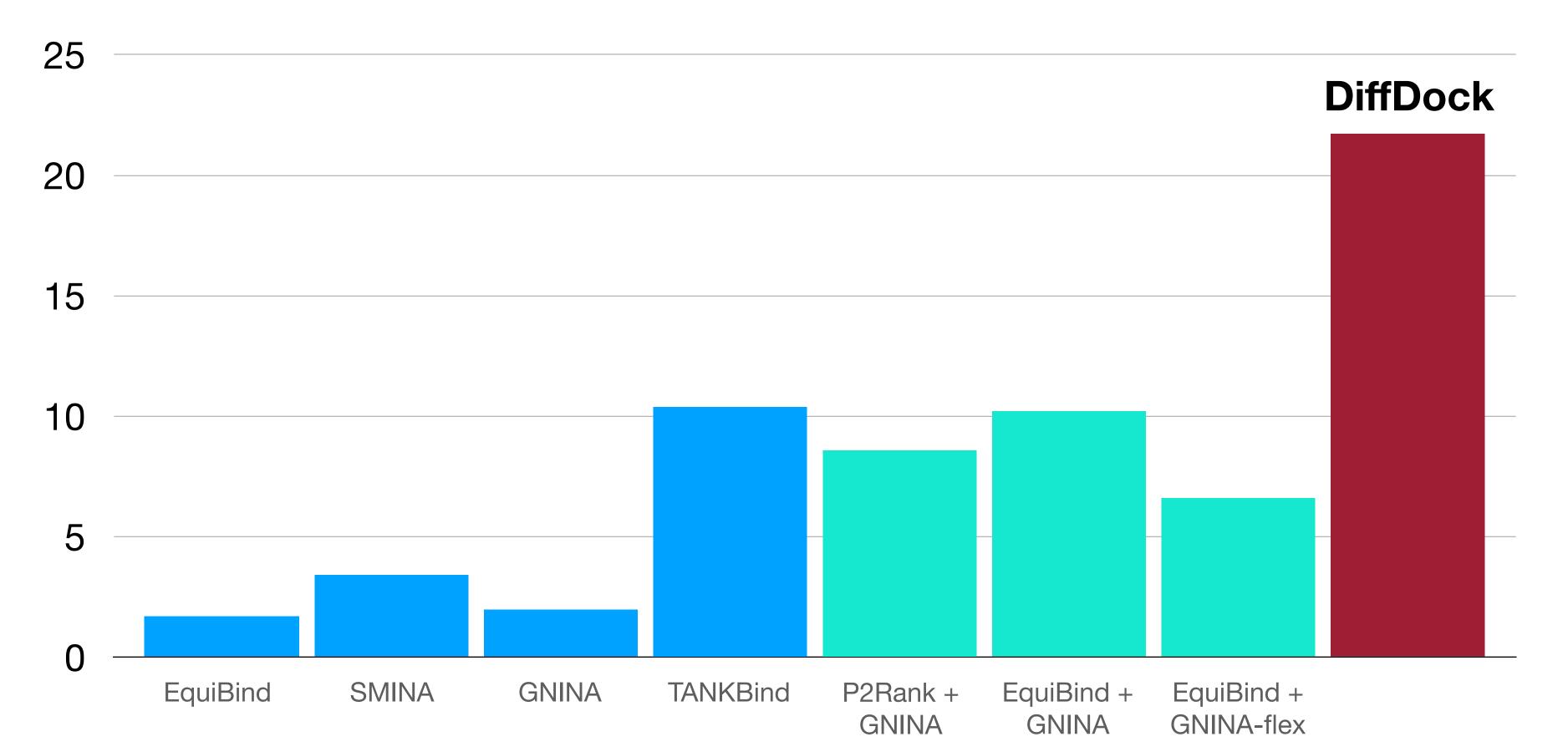


**Outperform** search-based, deep learning, and pocket prediction + search-based methods



# Blind docking on predicted structures

## Percentage of predictions with RMSD < $2\text{\AA}$



## Retains significantly higher accuracy on ESMFold structures





# **Diffusion Steps, Twists, and Turns** for Molecular Docking

#### **Gabriele Corso\***

### Hannes Stärk\*







## All links in our GitHub: <u>https://github.com/gcorso/DiffDock</u>



# DiffDock

#### **Bowen Jing\***

**Regina Barzilay** 



#### Tommi Jaakkola

